IN THE CLAIMS:

1. (Previously Presented) A method for determining a current distribution of an object, the method comprising:

measuring the magnetic fields in vicinity of the object using a multi-channel measurement device that measures an irrotational and sourceless vector field, whereby one measurement sensor corresponds to each channel;

converting a multi-channel measurement signal corresponding to each measurement sensor into the signals of a predetermined set of virtual sensors; and

determining the current distribution of the object being measured from the signals of the set of virtual sensors in a predetermined function basis to be efficiently calculated.

- 2. (Currently Amended) The method according to claim 1, wherein the object is approximated using a spherical-harmonic conductor, and a multi-pole development expansion of the field is calculated from the multi-channel measurement signal.
- 3. (Currently Amended) The method according to claim 2, wherein the multipole development expansion is calculated by taking into account magnetic fields emitted by sources outside the object.
- 4. (Currently Amended) The method according to claim 2, wherein the multipole development expansion is calculated by ignoring magnetic fields emitted by sources outside the object.
- 5. (Previously Presented) The method according to claim 2, wherein external interferences are eliminated prior to the step of converting.
- 6. (Currently Amended) The method according to claim 2, wherein as an orthonormal function basis, a current distribution equation of the following form is selected:

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$$\int_{l=0}^{\rho} \int_{m=-1}^{\rho} c_{lm} f(r) \frac{\rho}{X lm(\theta, \varphi)},$$

$$\vec{J}(\vec{r}) = \sum_{l=0}^{L} \sum_{m=-1}^{l} c_{lm} f_{l}(r) \vec{X} lm(\theta, \varphi),$$

wherein $\underline{c_{lm}}$ are coefficients of the current distribution, $\underline{f(r)}$ $\underline{f_l(r)}$ is a freely selectable radial function and $\underline{\overset{\rho}{X} lm(\theta, \varphi)}$ $\underline{\overset{\gamma}{X} lm(\theta, \varphi)}$ is vector spherical harmonic.

7. (Currently Amended) The method according to claim 4, wherein:
an orthonormal function basis is placed into a current distribution equation;
and

coefficients of the current distribution are analytically solved from the equation:

$$\frac{\hat{C}_{lm} - \hat{\gamma}_l M_{lm} \left[\int_0^R r^l f(r) dr \right]^{-1}}{\frac{1}{r}},$$

$$C_{lm} = \hat{\gamma}_l M_{lm} \left[\int_0^R r^{l+2} f_l(r) dr \right]^{-1},$$

wherein $\frac{\hat{\gamma}_I}{\hat{\gamma}_I}$ is a constant associated with order $1_{\underline{M_{lm}}}$ are multi-pole coefficients, and R is a radius of a sphere to be examined, and $\frac{\hat{\gamma}_I}{X lm(\theta, \phi)} f_I(r)$ is a freely selectable radial function spherical harmonic.

8. (Previously Presented) The method according to claim 4 $\underline{6}$, wherein function $\underline{f(r)}$ $\underline{f_l(r)}$ is used to adjust a depth weighing of a current distribution model.

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9. (Currently Amended) A measurement device for determining a current distribution of an object by measuring magnetic fields in <u>a</u> vicinity of the object, the measurement device comprising:

a set of measurement channels $(1, 1^1, 1^2, \dots 1^n)$ that measure an irrotational and sourceless a curl free and divergence free vector field, in which case at least one measurement sensor $2, 2^1, 2^2, \dots 2^n$ corresponds to each channel;

processing means for processing a measurement signal in which the object is approximated using a spherical-symmetrical conductor, wherein

the processing means include a conversion module for converting a multi-channel measurement signal corresponding to each measurement sensor into signals of a predetermined set of virtual sensors, which sensors are mutually orthogonal; and

calculation means for determining the current distribution of an object being examined from the set of virtual sensors using depth r in a predetermined orthonormal function basis.

- 10. (Currently Amended) The measurement device according to claim 9, wherein the calculation means are arranged to calculate a multi-pole development expansion from the multi-channel measurement signal.
- 11. (Currently Amended) The measurement device according to claim 10, wherein the multi-pole development expansion is calculated by taking into account magnetic fields emitted by sources outside the object being measured.
- 12. (Currently Amended) The measurement device according to claim 10, wherein the multi-pole development expansion is calculated by ignoring magnetic fields emitted by sources outside the object being measured.
 - 13. (Currently Amended) The measurement device according to claim 10,

wherein as the orthonormal function basis, a current distribution equation with the following form is selected:

$$\frac{\int_{l=0}^{\rho} \sum_{m=-l}^{l} c_{lm} f_l(r) \stackrel{\rho}{X} lm(\theta, \varphi),}{\int_{l=0}^{l} c_{lm} f_l(r) \stackrel{\rho}{X} lm(\theta, \varphi)}$$

$$\overrightarrow{J}(\overrightarrow{r}) = \sum_{l=0}^{L} \sum_{m=-l}^{l} c_{lm} f_{l}(r) \overrightarrow{X} lm(\theta, \varphi),$$

wherein $f(r) - f_l(r)$ is a radial function to be freely selected and $X lm(\theta, \varphi)$ is vector spherical harmonic.

14. (Currently Amended) The measurement device according to claim 12, wherein

the orthonormal function basis is placed into the current distribution equation; and coefficients of the current distribution are solved analytically from the equation:

$$C_{lm} = \gamma_l M_{lm} \left[\int_0^R r^l f(r) dr \right]^{-1},$$

$$C_{lm} = \hat{\gamma}_{l} M_{lm} \left[\int_{0}^{R} r^{l+2} f_{1}(r) dr \right]^{-1},$$

wherein γ_l $\hat{\gamma}_l$ is a constant associated with order 1 and R is a radius of a sphere to be examined and $f_l(r)$ is a radial function to be freely selected.

- 15. (Currently Amended) The measurement device according to claim 13, wherein $f(r) f_l(r)$ is used to adjust a depth weighing of a current distribution model.
- 16. (Previously Presented) The measurement device according to in claim 9, wherein the measurement device converts the signals into a set of virtual sensors prior to storage, and analysis software converts the stored data into a current distribution.

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17. (New) The method according to claim 2, wherein the object is approximated using a spherically symmetric conductor.

18. (New) The method according to claim 9, wherein the object is approximated using a spherically symmetric conductor.